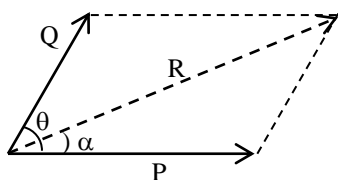


CHAPTER 04 - MOTION IN A PLANE

VECTORS

1) Unit vector $\hat{A} = \frac{\vec{A}}{|\vec{A}|}$

2) **Magnitude of addition of two vectors:**



Resultant of addition of two vectors P and Q making an angle of θ is $R = \sqrt{P^2 + Q^2 + 2PQ \cos \theta}$

Direction of the resultant force $\alpha = \tan^{-1}\left(\frac{Q \sin \theta}{P + Q \cos \theta}\right)$ where α is the angle between R and P

θ	R	α or Direction of resultant
0°	$R_{\max} = P + Q$	0° i.e. along given vectors
90°	$R = \sqrt{P^2 + Q^2}$	$\alpha = \tan^{-1}\left(\frac{Q}{P}\right)$
180°	$R_{\min} = P - Q$ (if $P > Q$)	0° or 180° i.e. along greater vector

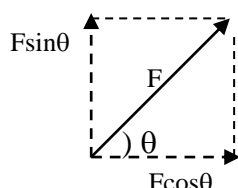
3) Resultant or addition of two identical vectors P making an angle θ between them is $R = 2P \cos\left(\frac{\theta}{2}\right)$

R makes an angle of $\theta/2$ with either vector.

4) When $P = Q$

θ	R	α
0°	$2P$	0°
60°	$\sqrt{3} P$	30°
90°	$\sqrt{2} P$	45°
120°	P	60°
180°	0	–

5) **Resolution of a vector:**



If F is a vector, which makes an angle θ with the x-axis then the component of F along x-axis is $F_x = F \cos \theta$ and the component of F along y-axis is $F_y = F \sin \theta$ also $F = \sqrt{F_x^2 + F_y^2}$

$$\tan \theta = \frac{F_y}{F_x}$$

6) **Representation of vector in one, two and three dimensional motion**

A vector in one dimensional motion along x-axis is given by $\vec{A} = x \hat{i}$ or $|\vec{A}| = x$

A vector in two dimensional motion in x-y plane is given by $\vec{A} = x \hat{i} + y \hat{j}$

$$|\vec{A}| = \sqrt{x^2 + y^2}$$

A vector in three dimensional motion is given by $\vec{A} = x \hat{i} + y \hat{j} + z \hat{k}$

$$|\vec{A}| = \sqrt{x^2 + y^2 + z^2}$$

where \hat{i} , \hat{j} and \hat{k} are the unit vectors along x, y and z axis respectively. Where x, y and z are its components along three axes respectively. Also $|\hat{i}| = |\hat{j}| = |\hat{k}| = 1$

7) Velocity of a body in two dimensions $\vec{v} = \vec{v}_x + \vec{v}_y = \frac{(x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j}}{t_2 - t_1}$

8) Dot product of two vectors \vec{A} and \vec{B} is denoted by $\vec{A} \cdot \vec{B}$

$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$ where θ is the angle between two vectors.

9) $|\vec{A} \cdot \vec{B}| = a_1 b_1 + a_2 b_2 + a_3 b_3$ where $\vec{A} = a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$ and $\vec{B} = b_1 \hat{i} + b_2 \hat{j} + b_3 \hat{k}$

\hat{i} , \hat{j} and \hat{k} are the unit vectors along x, y and z axis.

$$|\vec{A}| = \sqrt{a_1^2 + a_2^2 + a_3^2} \quad \text{and} \quad |\vec{B}| = \sqrt{b_1^2 + b_2^2 + b_3^2}$$

10) $\hat{i} \cdot \hat{i} = |\hat{i}| |\hat{i}| \cos\theta = 1 \times 1 \times \cos 0 = 1 \therefore \theta = 0^\circ$

Similarly $\hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$

$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0 \therefore \theta = 90^\circ$

11) $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$ (Dot product is commutative)

12) Cross product of two vectors \vec{A} and \vec{B} is denoted by $\vec{A} \times \vec{B}$
 $\vec{A} \times \vec{B} = |\vec{A}| |\vec{B}| \sin\theta (\hat{n})$ where θ is the angle between two vectors and \hat{n} is the unit vector.

13) $\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$

14) $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$

$\hat{i} \times \hat{j} = \hat{k}, \hat{j} \times \hat{k} = \hat{i}, \hat{k} \times \hat{i} = \hat{j}$

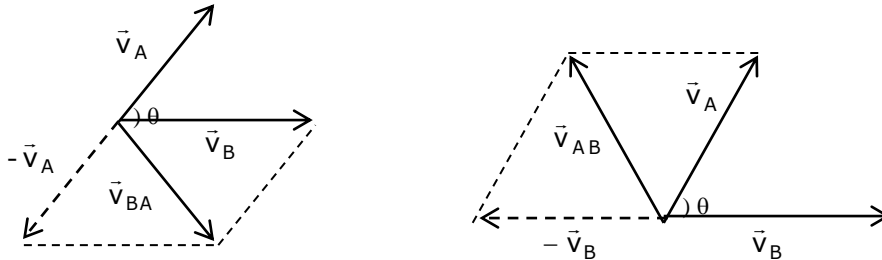
$\hat{j} \times \hat{i} = -\hat{k}, \hat{k} \times \hat{j} = -\hat{i}, \hat{i} \times \hat{k} = -\hat{j}$

15)
$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

16) **Relative velocity of two bodies moving in different directions:**

Relative velocity of A with respect to B is $\vec{v}_{AB} = \vec{v}_A - \vec{v}_B$

Relative velocity of B with respect to A is $\vec{v}_{BA} = \vec{v}_B - \vec{v}_A$



$|\vec{v}_{AB}| = |\vec{v}_A - \vec{v}_B| = \sqrt{v_A^2 + v_B^2 - 2v_A v_B \cos\theta}$

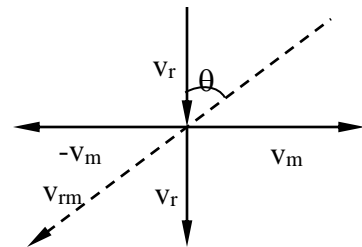
$|\vec{v}_{BA}| = |\vec{v}_B - \vec{v}_A| = \sqrt{v_A^2 + v_B^2 - 2v_A v_B \cos\theta}$

17) The angle through which man should hold umbrella with vertical to protect himself from rain which is

falling vertically downwards is $\tan\theta = \frac{v_m}{v_r}$

Relative velocity of rain w.r.t man is $v_{rm} = v_r - v_m$

$v_r =$ velocity of rain
 $v_m =$ velocity of man



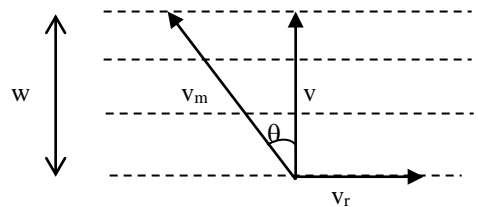
18) When a man tends to cross a river along a shortest path, he should swim upstream making an angle θ given

by $\sin\theta = \frac{v_r}{v_m}$

Time taken to cross the river over the shortest distance is

$t = \frac{w}{\sqrt{v_m^2 - v_r^2}} = \frac{w}{v}$

where resultant velocity $v = \sqrt{v_m^2 - v_r^2}$ v_m – velocity of man or boat; v_r – velocity of river



19) **When a man or a boat tends to cross the river in shortest time.**

Time taken to cross the river of width w in shortest possible time is $t = \frac{w}{v_m}$

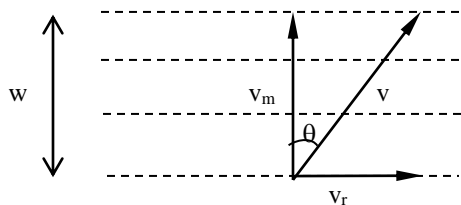
Resultant velocity $v = \sqrt{v_m^2 + v_r^2}$

$\tan\theta = \frac{v_r}{v_m}$

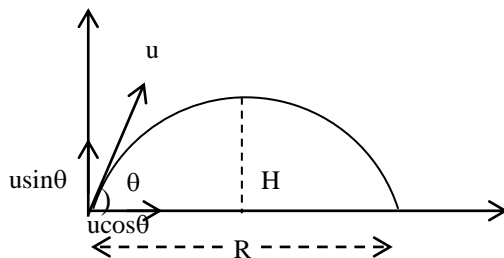
w – width of the river

v_m – velocity of man or boat

v_r – velocity of river water



OBLIQUE PROJECTILE MOTION



1)

	Along horizontal (x-axis)	Along vertical (y-axis)
Initial velocity	$u_x = u \cos \theta$	$u_y = u \sin \theta$
Acceleration	$a_x = 0$	$a_y = -g$
Velocity at maximum height	$v_x = u \cos \theta$	$v_y = 0$
Velocity at any instant t	$v_x = u \cos \theta$	$v_y = u_y - gt = u \sin \theta - gt$
Displacement	$x = u_x t = (u \cos \theta)t$	$y = u_y t - \frac{1}{2} g t^2$ $y = (u \sin \theta)t - \frac{1}{2} g t^2$

2)

Energy:

When a projectile moves upward its kinetic energy decreases, potential energy increases but the total energy always remains constant.

- Initial kinetic energy $K = \frac{1}{2} m u^2$
- Initial potential energy $U = 0$
- **At the highest point:**
- Kinetic energy $K' = \frac{1}{2} m (u \cos \theta)^2 = K \cos^2 \theta$
- Potential energy $U = mgH = \frac{1}{2} m u^2 \sin^2 \theta = K \sin^2 \theta$
- Total energy $E = K + U = \frac{1}{2} m u^2 = \text{energy at the point of projection.}$

3)

Instantaneous velocity:

- Vertical velocity $v_y = u_y - gt = u \sin \theta - gt$
- Horizontal velocity $v_x = u_x = u \cos \theta$
- The resultant velocity $\vec{v} = v_x \hat{i} + v_y \hat{j}$ or $v = \sqrt{v_x^2 + v_y^2}$
- The direction of the velocity w.r.t horizontal is $\alpha = \tan^{-1} \left(\frac{v_y}{v_x} \right)$

4)

Velocity at a given height:

- Vertical velocity $v_y = \sqrt{u_y^2 - 2gh} = \sqrt{u^2 \sin^2 \theta - 2gh}$
- Horizontal velocity $v_x = u_x = u \cos \theta$
- The resultant velocity $\vec{v} = v_x \hat{i} + v_y \hat{j}$ or $v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 - 2gh}$
- The direction of the velocity w.r.t horizontal is $\alpha = \tan^{-1} \left(\frac{v_y}{v_x} \right)$

5)

Angular momentum:

Angular momentum of the projectile at highest point of trajectory about the point of projection:

$$L = mvr = mvH = m(u \cos \theta) \left(\frac{u^2 \sin^2 \theta}{2g} \right) = \frac{m u^3 \cos \theta \sin^2 \theta}{2g}$$

6)

Equation of trajectory:

- $y = ax - bx^2 = x \tan \theta \left(1 - \frac{x}{R} \right)$ where $a = \tan \theta$ and $b = \left(\frac{g}{2u^2 \cos^2 \theta} \right)$ are constant
- Horizontal range $R = \frac{a}{b} = \frac{u^2 \sin 2\theta}{g}$

7)

Time of Flight:

- Time of ascent = Time of descent $t = \frac{T}{2} = \frac{u \sin \theta}{g}$
- $T = \frac{2u_y}{g} = \frac{2u \sin \theta}{g}$

8)

Maximum Height:

- $H = \frac{u_y^2}{2g} = \frac{u^2 \sin^2 \theta}{2g}$
- For maximum height, body should be thrown vertically upward ($\theta = 90^\circ$)
- $H_{\max} = \frac{u^2}{2g}$

9) Time of flight and maximum height H depends only on u_y

If two projectiles thrown in different directions have equal time of flight then their initial vertical velocities are same so that their maximum height is also same.

10) **Range:**

$$R = (u \cos \theta)T = \frac{2u_x u_y}{g} = \frac{u^2 \sin 2\theta}{g}$$

Maximum range:

• For a given velocity of projection the range is maximum (R_{\max}), if the angle of projection is 45° .

$$R_{\max} = \frac{u^2}{g} = 4H$$

$$\text{Maximum height } H = \frac{u^2}{4g} = \frac{R_{\max}}{4}$$

$$\text{Time of flight } T = \sqrt{\frac{2R_{\max}}{g}}$$

11) **Relation between range and maximum height:**

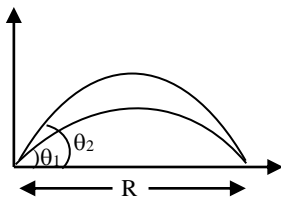
$$R = 4H \cot \theta$$

$$\text{If } R = nH, \theta = \tan^{-1}\left(\frac{4}{n}\right)$$

$$\text{If } R = H, \theta = \tan^{-1}(4) = 76^\circ$$

$$\text{If } R = 4H, \theta = \tan^{-1}(1) = 45^\circ$$

12) **When two projectiles are projected with same velocities at complementary angles:**



• When two projectiles are projected with same velocity at two different angles of projection θ and $(90 - \theta)$ (complementary angles) then they cover same range.

$$\frac{R_1}{R_2} = 1$$

• For a given velocity if T_1 and T_2 are the time of flights for two angles of projection, then $T_1 T_2 = \frac{2R}{g}$

$$\text{Ratio of time flights } \frac{T_1}{T_2} = \tan \theta$$

$$\text{Range of the projectile is } R = 4\sqrt{H_1 H_2} \text{ or } H_1 H_2 = \frac{R^2}{16}$$

where H_1 and H_2 are the heights reached by the projectiles.

$$\text{Ratio of maximum height } \frac{H_1}{H_2} = \tan^2 \theta$$

$$H_1 + H_2 = \frac{u^2}{2g}$$

13) **Projectile projected along horizontal:**

• Velocity of projection $u_x = u, u_y = 0$

• Acceleration $a_x = 0; a_y = g$

$$\text{Horizontal displacement } x = u_x t \text{ or } t = \frac{x}{u}$$

$$\text{Vertical displacement } y = \frac{1}{2} g t^2 = \frac{1}{2} \frac{g x^2}{u^2}$$

$$\text{Position vector: } \vec{r} = x\hat{i} + y\hat{j} = ut\hat{i} + \frac{1}{2}gt^2\hat{j}$$

$$\text{Time of flight } T = \sqrt{\frac{2h}{g}} \text{ or } h = \frac{1}{2} g T^2$$

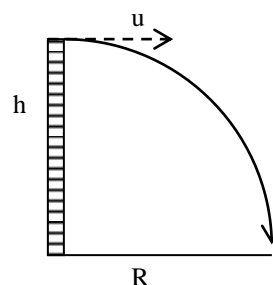
Time taken by the projectile to reach the ground does not depend upon the velocity of projection.

$$\text{Horizontal range } R = uT = u \sqrt{\frac{2h}{g}}$$

$$\text{Instantaneous velocity: } v_x = u; v_y = gt = \sqrt{2gh}$$

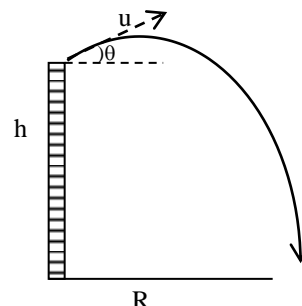
$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 + g^2 t^2} = \sqrt{u^2 + 2gh}$$

$$\text{Direction of velocity } \alpha = \tan^{-1}\left(\frac{v_y}{v_x}\right)$$



14) **Projection from a height at an angle θ above horizontal:**

- Velocity of projection $u_x = u \cos \theta$, $u_y = -u \sin \theta$
- Acceleration $a_x = 0$; $a_y = g$ (net displacement downward)
- Horizontal displacement $x = (u \cos \theta)t$ or $t = \frac{x}{u \cos \theta}$
- Vertical displacement $y = -(u \sin \theta)t + \frac{1}{2}gt^2$
- Position vector: $\vec{r} = x\hat{i} + y\hat{j}$
- Height: $h = -(u \sin \theta)t + \frac{1}{2}gt^2$
 $h + (u \sin \theta)t - \frac{1}{2}gt^2 = 0$
- Horizontal range $R = (u \cos \theta)t$
- **Velocity after falling height h:**



$$v_y^2 = (-u \sin \theta)^2 + 2gh$$

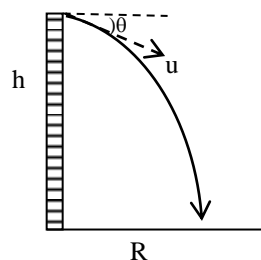
$$v_x = u_x = u \cos \theta$$

$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 + 2gh}$$

$$\text{Direction of velocity } \alpha = \tan^{-1} \left(\frac{v_y}{v_x} \right)$$

15) Projection from a height at an angle θ below horizontal:

- Velocity of projection $u_x = u \cos \theta$, $u_y = u \sin \theta$
- Acceleration $a_x = 0$; $a_y = g$
- Horizontal displacement $x = (u \cos \theta)t$ or $t = \frac{x}{u \cos \theta}$
- Vertical displacement $y = (u \sin \theta)t + \frac{1}{2}gt^2$
- Position vector: $\vec{r} = x\hat{i} + y\hat{j}$
- Height: $h = (u \sin \theta)t + \frac{1}{2}gt^2$
 $h - (u \sin \theta)t - \frac{1}{2}gt^2 = 0$
- Horizontal range $R = (u \cos \theta)t$
- **Velocity after falling height h:**



$$v_y^2 = (u \sin \theta)^2 + 2gh$$

$$v_x = u_x = u \cos \theta$$

$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{u^2 + 2gh}$$

$$\text{Direction of velocity } \alpha = \tan^{-1} \left(\frac{v_y}{v_x} \right)$$

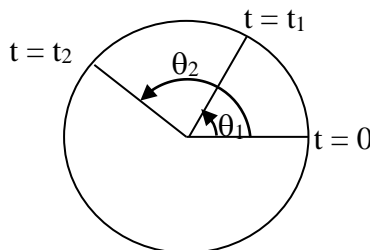
Uniform circular motion

- 1) Angular displacement of particle $d\theta = ds/r$
where ds is the distance covered and r is the radius of circular path
- 2) Vector form $\vec{ds} = \vec{d\theta} \times \vec{r}$
- 3) If $d\theta$ is the angular displacement in time dt then instantaneous angular velocity

$$\omega = \frac{d\theta}{dt} \text{ (rads}^{-1}\text{)}$$

- 4) Average angular velocity $\omega_{av} = \frac{\theta_2 - \theta_1}{t_2 - t_1} = \frac{\Delta\theta}{\Delta t}$

where θ_1 and θ_2 are the angular positions of the particle at instants t_1 and t_2



- 5) The number of revolutions made per second is called frequency of revolution,

$$f = \frac{1}{T}$$

- 6) If ' r ' is the radius of the path and T is the period of revolution then linear speed $v = \frac{2\pi r}{T} = 2\pi r f$

- 7) Relation between linear velocity and angular velocity:

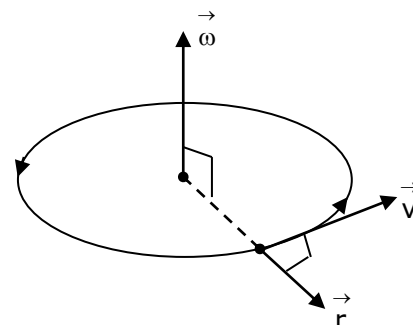
$$v = r \omega$$

$$\text{Vector form } \vec{v} = \vec{\omega} \times \vec{r}$$

\vec{v} = linear velocity (tangential); $\vec{\omega}$ = angular velocity (along axis)

\vec{r} = radius vector (along radius directed away from centre)

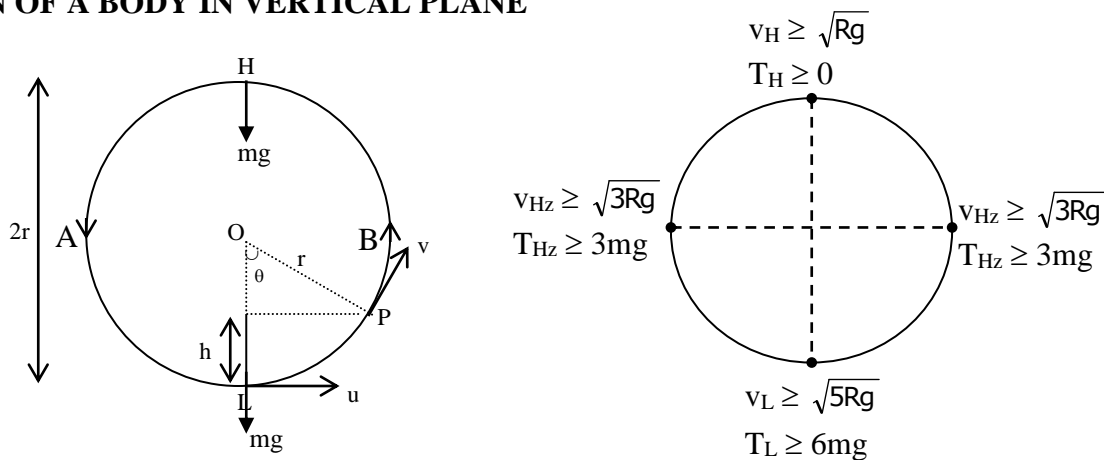
$$\text{Here } \vec{v} \perp \vec{\omega} \perp \vec{r} \Rightarrow \vec{v} \cdot \vec{\omega} = 0; \vec{v} \cdot \vec{r} = 0; \vec{\omega} \cdot \vec{r} = 0$$



- 8) Angular velocity $\omega = \frac{\theta}{t} = \frac{2\pi}{T} = 2\pi f$

- 9) Centripetal acceleration $a = \omega^2 r = \frac{v^2}{r} = v\omega$
- 10) The centripetal acceleration produced in a particle is because of the centripetal force acting on it.
Centripetal force $F = m\omega^2 r = \frac{mv^2}{r} = mv\omega$
where m is the mass of the particle.
- 11) Direction of velocity and displacement are along the tangent to the circular path.
- 12) The centripetal acceleration and centripetal force are directed towards the centre along the radius of the circular path.
- 13) The velocity and acceleration vectors are perpendicular to each other.
- 14) Work done by the centripetal force $W = Fs \cos 90 = 0$. (\because F and s are perpendicular to each other)
- 15) Tangential acceleration $a_T = 0$ hence angular acceleration $\alpha = 0$
- 16) The quantities, which remain constant in uniform circular motion, are speed v , kinetic energy K , angular velocity ω and angular momentum L .
The quantities that changes are velocity v , momentum p , radial (or centripetal) acceleration a_R and centripetal force F_c .

MOTION OF A BODY IN VERTICAL PLANE



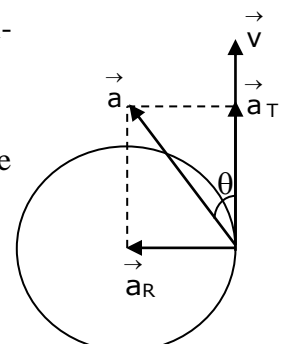
Consider a body of mass m tied to one end of a string of length r is rotated in a vertical circle of radius r . It is imparted a velocity u in the horizontal direction at lowest point L .

- 1) Tension at any position P of angular displacement (θ) along vertical circle is
$$T = \frac{mv^2}{r} + mg \cos \theta$$
- 2) Tension in the string is maximum when the body is at the lowest point L ($\theta = 0^\circ$)
$$T_L = \frac{mv_L^2}{r} + mg$$
- 3) Tension in the string is minimum when the body is at the highest point H ($\theta = 180^\circ$)
$$T_H = \frac{mv_H^2}{r} - mg$$
- 4) Body oscillates in lower half circle between A and B if $0 < u \leq \sqrt{3gr}$
- 5) Body moves to upper half circle but not able to complete loop if $\sqrt{3gr} < u < \sqrt{5gr}$
After leaving the circle, the particle will follow a parabolic path.
- 6) **For circling the loop**
- Velocity required at the highest point H is $v_H \geq \sqrt{gr}$
Tension in the string is $T_H \geq 0$
 - When the string is horizontal ($\theta = 90^\circ$) velocity is $v_{Hz} \geq \sqrt{3gr}$
Tension in the string is $T_{Hz} \geq 3mg$
 - Velocity required at the lowest point L is $v_L \geq \sqrt{5gr}$
Tension in the string is $T_L \geq 6mg$

NON-UNIFORM CIRCULAR MOTION:

If a body moves with variable speed in a circle, then the motion is called non-uniform circular motion.

- 1) In this motion acceleration 'a' has two components:
Centripetal or Radial acceleration $a_R = v\omega = \omega^2 r = \frac{v^2}{r}$ responsible for change in direction only
Tangential acceleration $a_T = r\alpha$ responsible for change in speed only
- 2) Net acceleration $\vec{a} = \vec{a}_R + \vec{a}_T$ or $|\vec{a}| = \sqrt{a_R^2 + a_T^2}$
- 3) Net force $\vec{F} = \vec{F}_R + \vec{F}_T$ or $|\vec{F}| = \sqrt{F_R^2 + F_T^2}$
- 4) As speed v is variable, kinetic energy $K = \frac{1}{2} mv^2$ changes



-
- 5) Work done by centripetal force will be zero but work done by tangential force is not zero.
Work done $W = F_T s$, where s is the distance travelled by the body
- 6) Angle between velocity and net acceleration, $\tan\theta = \frac{a_R}{a_T}$